	The freeness problem	

The freeness problem on matrix groups Summer research 2021 (Supervisor: Emmanuel Breuillard)

Georgi Kocharyan

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October 12, 2021

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Important preliminary: Concepts of *algorithms* and *undecidability*. Turing 1936: Turing machine (TM) as model of computation, consisting of:

- An (infinite) tape of 0s and 1s, and a tape head
- A finite amount of 'states' dictating the behaviour of the TM depending on if head is on a 0 or a 1

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Figure: Depiction of a TM¹

¹http://science.slc.edu/ jmarshall/courses/2002/fall/cs30/Lectures/week08/TuringMachine.gff > 📱 🔗 < 🗠 4/15

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Figure: Depiction of a TM¹

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A problem is *undecidable* if there exists no Turing machine always outputting the correct solution to it.

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Halting problem: Can we find a TM that can, given another TM, always predict whether or not this TM will halt on a given input?

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Examples:

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а	ab	bba
baa	аа	bb

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What if we fix n? In this case the PCP becomes decidable for $n \le 2$, but remains undecidable for $n \ge 5$.

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- $\mathbb{F} \times \mathbb{F}$: decidable (exercise)

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$$\sigma(a_{i_1} \cdots a_{i_k}) = \sum_{j=1}^k i_j n^{k-j}$$

$$\gamma : \mathbb{W} \times \mathbb{W} \to \mathbb{N}^{3 \times 3}$$

$$(u, v) \mapsto \begin{pmatrix} n^{|u|} & 0 & 0 \\ 0 & n^{|v|} & 0 \\ \sigma(u) & \sigma(v) & 1 \end{pmatrix}$$

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Cassaigne, Harju, Karhumäki (1999): No such morphism exists for $\mathbb{C}^{2\times 2}$.

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- For matrix groups: open problem

Let G be a finitely generated matrix group.

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Definition (Membership problem or generalised word problem)

Given a finite set of words $\{g_1, \ldots, g_k\}$ in the generators and another word w, determine whether $w \in \langle g_1, \ldots, g_k \rangle$ or not.

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Definition (Conjugacy problem)

Given two words in the generators determines whether they are conjugate within G or not.

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Theorem

The membership problem is undecidable for groups of $4\times4-matrices.$

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If G has undecidable word problem, then w = 1 in G is equivalent to $(w, 1) \in M(G)$.

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If G has undecidable word problem, then w = 1 in G is equivalent to $(w, 1) \in M(G)$. Then just embed M(G) into $GL_4(\mathbb{Z})$.

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Theorem

The conjugacy problem is undecidable for groups of $4 \times 4-matrices$.

Proof.

Add x to the generators and relators of G. Then w = 1 in G if and only if (x, x) is conjugate to $(x, w^{-1}xw)$ in M(G). (Exercise!)

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Hyperplane problem

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The matrix mortality problem for a matrix semigroup G asks for an algorithm which given a finite set of matrices $\{G_1, \ldots, G_k\} \subseteq G$ determines whether $0 \in \{G_1, \ldots, G_k\}^+$.

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The upper-left-corner problem or hyperplane problem for a matrix semigroup G asks for an algorithm which given a finite set of matrices $\{G_1, \ldots, G_k\} \subseteq G$ determines whether $\exists M \in \{G_1, \ldots, G_k\}^+$ with $M_{11} = 0$.

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Definition

The upper-left-corner problem or hyperplane problem for a matrix semigroup G asks for an algorithm which given a finite set of matrices $\{G_1, \ldots, G_k\} \subseteq G$ determines whether $\exists M \in \{G_1, \ldots, G_k\}^+$ with $M_{11} = 0$.

Lemma

The solvability of the mortality problem for $\operatorname{GL}_3(\mathbb{Z})$ implies the solvability of the upper left corner problem for $\operatorname{GL}_3(\mathbb{Z})$.

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	Further matrix group problems	
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Theorem (Halava and Harju, 2001)

The upper-left-corner problem is undecidable for sets of 5 3×3 -integer matrices.

Note that this is for semigroups.

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	Further matrix group problems	Free subgroups of SO_3
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Note that this is for semigroups. What happens for groups?

Theorem (Result from placement)

The upper-left-corner problem for groups is undecidable for sets of 17 6×6 -rational matrices.

This is achieved by reducing to the membership problem!

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Free subgroups of SO_3

Motivated by study of Banach-Tarski paradox.



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Free subgroups of SO_3

Motivated by study of Banach-Tarski paradox.

$$r_x^{\pm\alpha} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos\alpha & \mp \sin\alpha \\ 0 & \pm \sin\alpha & \cos\alpha \end{pmatrix} \qquad r_z^{\pm\alpha} = \begin{pmatrix} \cos\alpha & \mp \sin\alpha & 0 \\ \pm \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

are the rotations by an angle α around the x and z axis respectively. We ask for what α we have that $\langle r_x^{\alpha}, r_z^{\alpha} \rangle$ is a free group of rank 2.



Free subgroups of SO_3

A few results on this:



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Free subgroups of SO_3

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Theorem (Result from placement)

If $\cos \alpha = \frac{2q}{q^2+1}$ for $q \in \mathbb{Q}, q \neq 0, 1$ then the rotation matrices by α around the x and z axes generate a free group.

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Theorem (Swierczkowski, 1994)

If $\cos \alpha \in \mathbb{Q} \setminus \{0, \pm \frac{1}{2}, \pm 1\}$, then the rotation matrices by α around the x and z axes generate a free group.

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